## ANALOG

 PRODUCTS
## MC33887

FACT SHEET

## APPLICATIONS

- Automotive Systems
- DC-M otor Control in Industrial and Robotic Systems
- DC-M otor and Actuator Control in Boats, RVs, and M arine Systems
- Appliance and White Goods Electrical Actuators
- Powered M achine and Hand Tools
- Antenna Rotors or Dish Positioning Systems


## 33887 5.2 AM P H-BRIDGE WITH SLEEP MODE

The 33887 is a monolithic H -Bridge that is ideal in applications to control fractional horsepower DC-motors or bi-directional thrust solenoids. The IC incorporates internal control logic, charge pump, gate drive, and low $\mathrm{R}_{\mathrm{DS}(\text { (on })} \mathrm{M}$ OSFET output circuitry. The 33887 is able to control continuous inductive DC load currents to 5.2 A. Output loads can be Pulse W idth M odulation (PW M ) controlled at frequencies to 10 kHz . A unique output monitoring circuit (current re-copy) makes available ground referenced load current feedback for implementation of closed-loop control of output current.

A Fault Status output reports under voltage, over current, and over temperature conditions. Two independent inputs control the two half-bridge totem-pole outputs making possible forw ard, reverse, freew heeling low, and freew heeling high active output states. Two complementary disable inputs are provided, the either of which can place the outputs in a high impedance "OFF" state.

The 33887 is operational over a wide range of conditions and is available in an economical surface mount package.

Simplified Application Diagram


## CUSTOMER BENEFITS

- Easiest way to interface a microcontroller to a DC-motor
- Simplified system design
- Built-in current limiting
- Built-in thermal shutdown
- Versatile output control
(each Totem-Pole output is independently controlled)
- Reduced board space
- Enhanced reliability

| Performance | Typical Values |
| :--- | :---: |
| Outputs | 2 |
| RM S Current | 5.2 A |
| RDS(on) @ $25^{\circ} \mathrm{C}$ | $120 \mathrm{~m} \Omega$ |
| Operating Voltage | $5.0-30 \mathrm{~V}$ |
| Peak Current | 8.0 A each output |
| Switching Time | $5.0 \mu \mathrm{~S}$ |
| ESD | $\pm 2000 \mathrm{~V}$ |
| Operating Temp | $-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq 125^{\circ} \mathrm{C}$ |
| J unction Operating Temp | $-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{J}} \leq 150^{\circ} \mathrm{C}$ |

## FEATURES

- Withstands $40 \mathrm{~V} \mathrm{~V}_{\text {BAT }}$ transients
- $120 \mathrm{~m} \Omega$ RDS(ow)
- Logic inputs TTL/CM OS compatible
- 10 kHz typical PWM frequency
- Power-saving sleep mode
- Diagnostic status flag output, current mirror output
- Additional devices available for comparison in Analog Selector Guide SG1002/D

| Protection | Detect | Limiting | Shut Down | Auto Retry | Status Reporting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Under Voltage | - |  | - | - | - |
| Over Current/SC | - | - |  | - | - |
| Over Temperature | - | - | - | - | - |
| Open Load | - |  |  |  | - |
| Short to GND | - | - |  | - | - |
| Short to VPW R | - | - |  | - | - |


| Ordering Information | Package | Ship Method | Motorola Part Number |
| :---: | :---: | :---: | :---: |
|  | 54 SOICW | Rail <br> T/R | **33887DW B <br> **33887DW BR2 |
|  | 44 QFN | $\begin{aligned} & \text { Rail } \\ & T / R \end{aligned}$ | $\begin{aligned} & * * 33887 F C \\ & * * 33887 F C R 2 \end{aligned}$ |
|  | 20 HSOP | $\begin{aligned} & \text { Rail } \\ & T / R \end{aligned}$ | $\begin{aligned} & * * 33887 \text { DH } \\ & \text { **33887DHR2 } \end{aligned}$ |
| Data Shee | Order Num |  | MC33887/D |
| Contact Sales for Evaluation Kit Availability |  |  |  |
| $\begin{aligned} & * * \text { Prefix In } \\ & P C=\text { Eng } S \end{aligned}$ | dex: Samples; XC | n Qual; | C = Production |

## QUESTIONS

- Do you need to control a DC-motor via microprocessor?
- Are you designing a DC-motor controller for motors up to 5.2 A and up to 30 V DC?
- Do you need to drive a motor in both forward and reverse or a solenoid in both push and pull?
- Do you need to incorporate PWM speed and torque control?
- Do you need to provide active braking and freewheeling?

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